Exponentially Faster Shortest Paths in the Congested Clique

Michal Dory (Technion), Merav Parter (Weizmann Institute)



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poly(log log n) round algorithms for approximate
 shortest paths in the Congested Clique



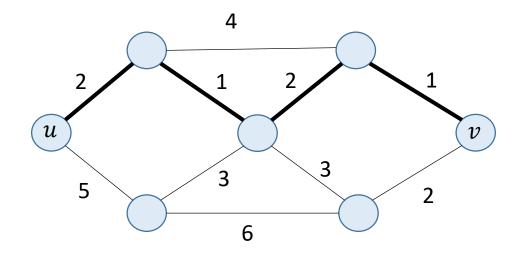
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- Background & our results
- Techniques:
 - Near-additive emulators
 - Distance sensitive toolkit

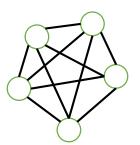
Background & Our Results

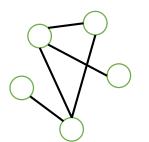
Distance Computation

- All-pairs shortest paths (APSP)
- Single-source shortest paths (SSSP)
- Multi-source shortest paths (MSSP)



The Congested Clique Model





Communication Network Input Graph

- *n* vertices
- Synchronous rounds, $\Theta(\log n)$ -bit messages
- All-to-All communication
- Input and output are local

Previous Work

• Polynomial time algorithms for exact APSP based on matrix multiplication [Censor-Hillel et al. 15, Le Gall 16]

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Round Complexity	Variant
$\tilde{O}(n^{1/3})$	weighted directed
$O(n^{0.158})$	unweighted undirected

Previous Work

- Polynomial time algorithms for exact APSP based on matrix multiplication [Censor-Hillel et al. 15, Le Gall 16]
- Poly-logarithmic algorithms for approximate shortest paths [Becker et al. 17, Censor-Hillel et al. 19]

Previous Work: Approximations

Round Complexity	Problem	Reference
$O(\epsilon^{-3} \operatorname{polylog} n)$	$(1 + \epsilon)$ -SSSP	[Becker, Karrenbauer, Krinninger, Lenzen '17]
$O(\log^2 n/\epsilon)$	$(1 + \epsilon)$ - MSSP with $O(\sqrt{n})$ sources	[Censor-Hillel, D,
$O(\log^2 n/\epsilon)$	$(3 + \epsilon)$ - APSP	Korhonen, Leitersdorf, '19]
$O(\log^2 n/\epsilon)$	$(2 + \epsilon)$ -unweighted APSP	

• All results are for **weighted undirected** graphs, unless specified otherwise

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Can we get faster algorithms?

- In the matrix multiplication algorithms, in iteration i we deal with paths of 2^i edges
- We need log *n* iterations

Our Results

Unweighted undirected graphs:

	$(1 + \epsilon)$ -MSSP with $O(n^{1/2})$ sources $(2 + \epsilon)$ -APSP

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$poly(\log \log n)$	•	$(1 + \epsilon)$ -MSSP with $O(n^{1/2})$ sources
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Our Results

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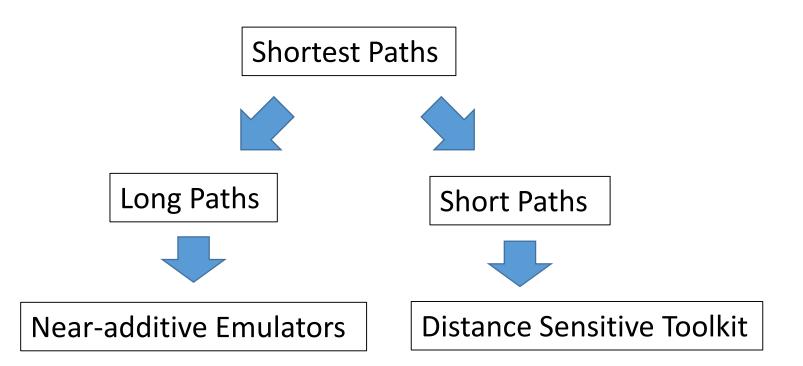
	$(1 + \epsilon)$ -MSSP with $O(n^{1/2})$ sources $(2 + \epsilon)$ -APSP

The APSP approximation is near-tight:

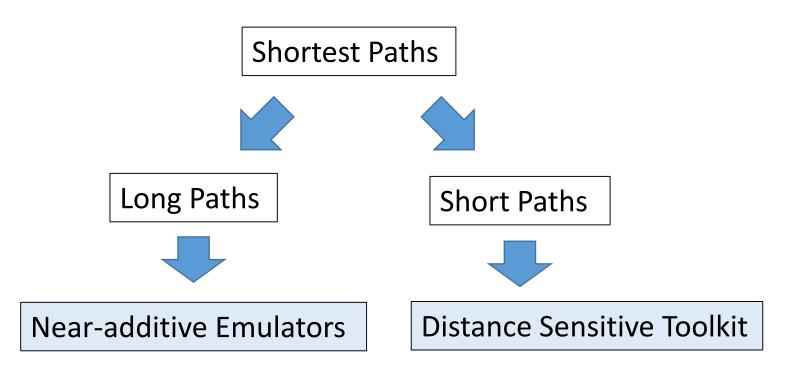
$(2 - \epsilon)$ -APSP implies	[Dor, Halperin, Zwick '00
Matrix Multiplication	Korhonen, Suomela '18]

Techniques

Our Techniques



Our Techniques



How to Get Faster Algorithms?

• $poly(\log n)$ looks like a natural barrier

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- $poly(\log n)$ looks like a natural barrier
- But maybe we can improve the approximation?

APSP Approximation

• $(2 + \epsilon)$ -approximation for APSP: $\delta(u, v) \le (2 + \epsilon)d(u, v)$

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Much better for long distances!

Near-Additive Emulator

A sparse graph H such that for all u, v: $d(u, v) \le d_H(u, v) \le (1 + \epsilon)d(u, v) + \beta$

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Build near-additive emulator with $O(n \log \log n)$ edges



Collect it by all vertices in $O(\log \log n)$ rounds

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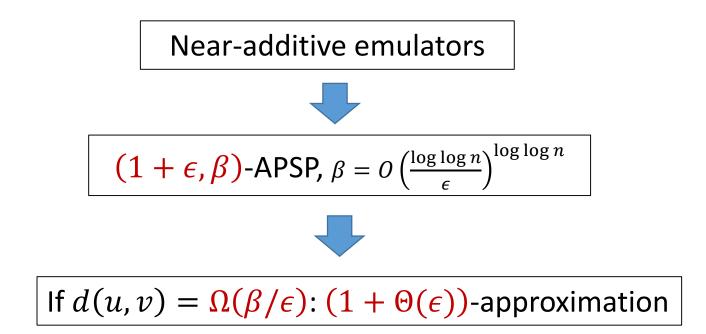
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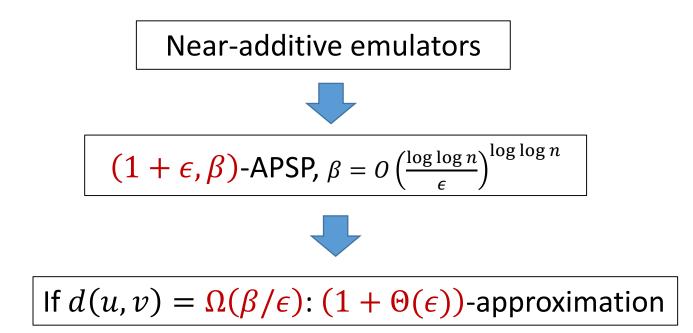
Build near-additive emulator with $O(n \log \log n)$ edges



Collect it by all vertices in $O(\log \log n)$ rounds

$$(1 + \epsilon, \beta)$$
-APSP, for $\beta = O\left(\frac{\log \log n}{\epsilon}\right)^{\log \log n}$

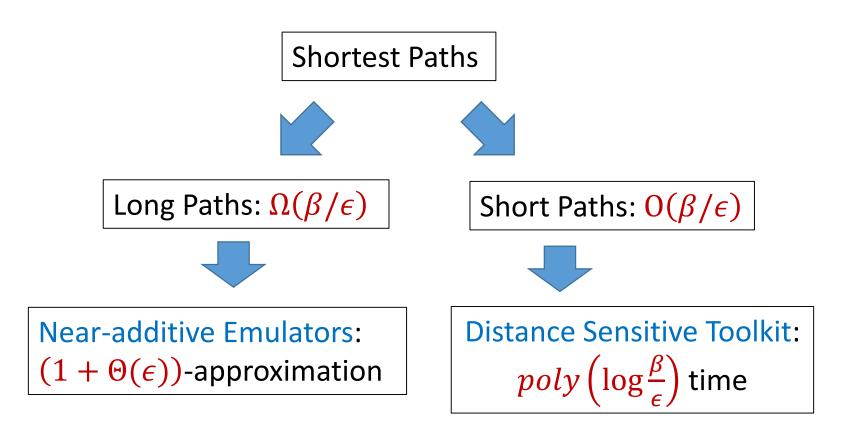


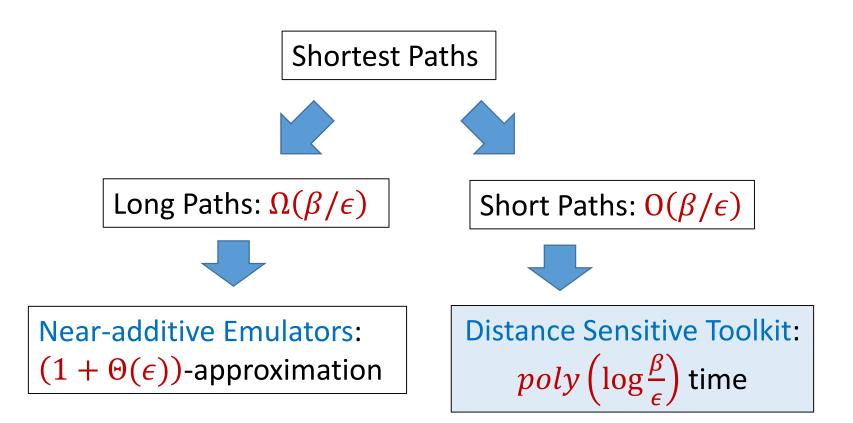


Left with short paths of length $t = O(\beta/\epsilon)$

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Requires $poly(\log t) = poly(\log \log n)$ time!





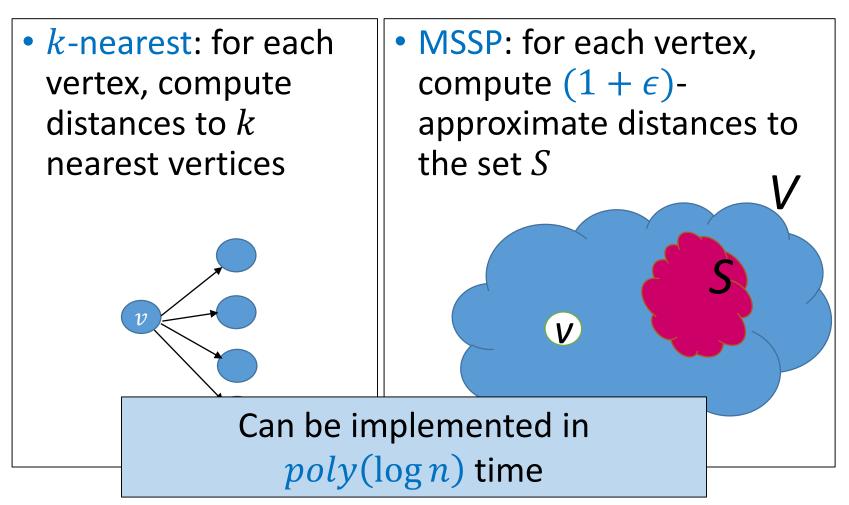
Distance Tools

[Censor-Hillel, D, Korhonen, Leitersdorf, '19]

• *k*-nearest: for each MSSP: for each vertex, compute $(1 + \epsilon)$ vertex, compute approximate distances to distances to kthe set S nearest vertices 12 V

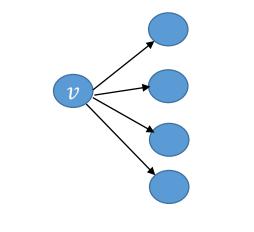
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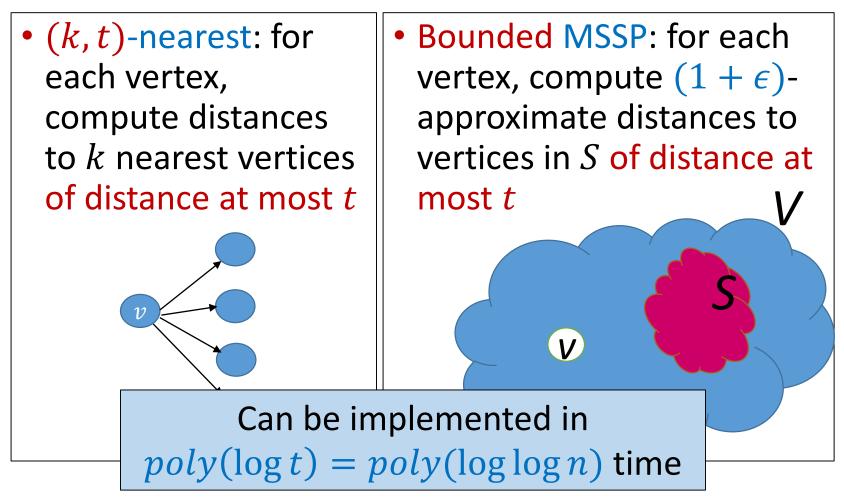
Distance Sensitive Tools

 (k, t)-nearest: for each vertex, compute distances to k nearest vertices of distance at most t

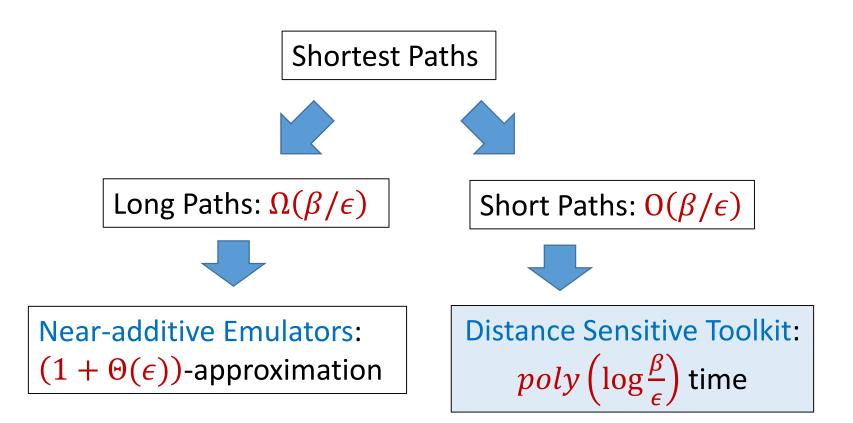


Bounded MSSP: for each vertex, compute $(1 + \epsilon)$ approximate distances to vertices in S of distance at most t 1/

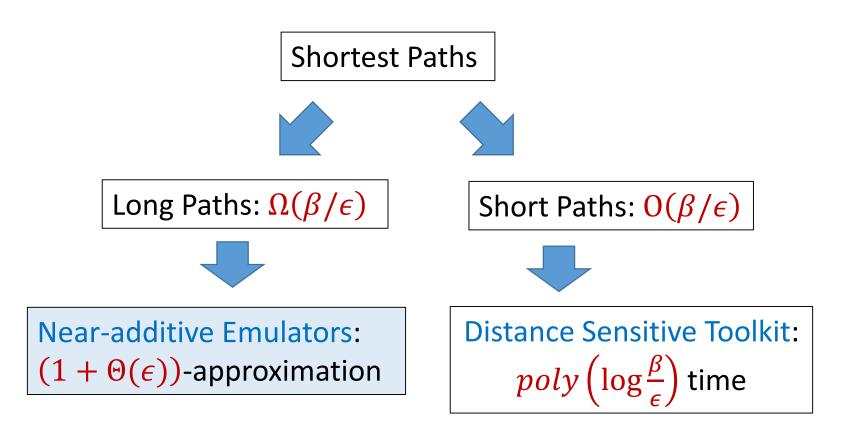
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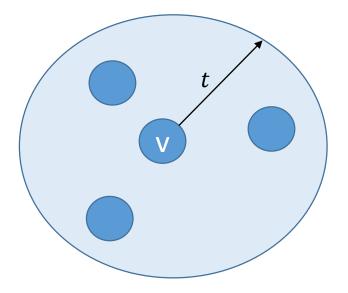
Shortest Paths via Emulators



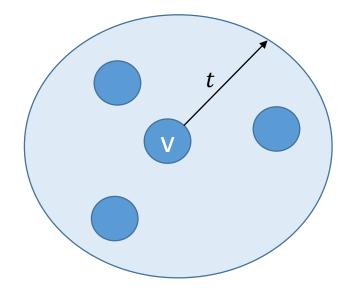
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• Each vertex inspects its $t = O(\beta/\epsilon)$ -radius ball, and adds to the emulator edges to some of these vertices



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- Can be implemented in *poly*(log t) = *poly*(log log n) time using the distance sensitive toolkit



Inspired by [Elkin-Neiman, 2018] and [Thorup-Zwick, 2006]

We construct:

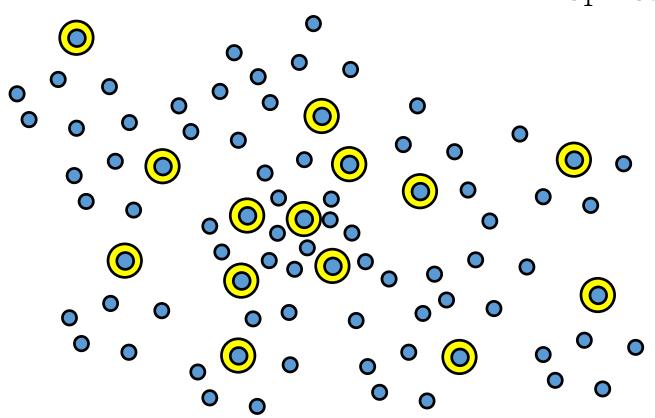
$$\left(1+\epsilon, O\left(\frac{r}{\epsilon}\right)^{r-1}\right)$$
-emulator with $O\left(rn^{1+1/2^r}\right)$ edges

• Choosing $r = \log \log n$ gives:

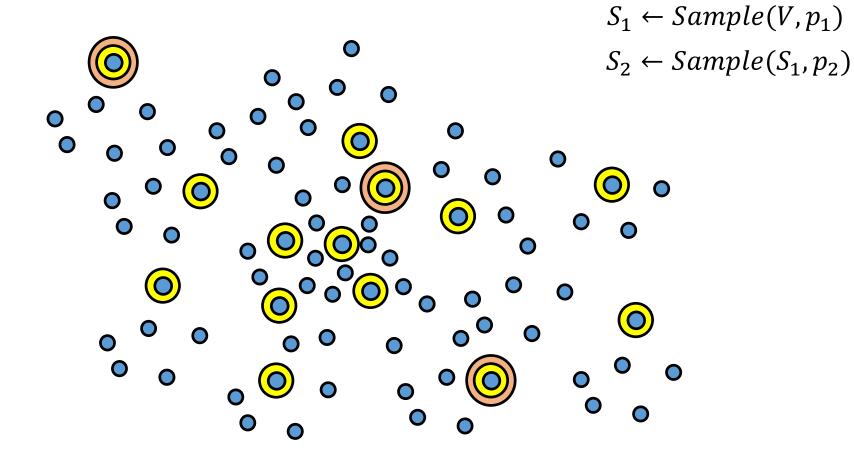
 $(1 + \epsilon, \beta) \text{-emulator with } O(n \log \log n) \text{ edges,}$ where $\beta = O\left(\frac{\log \log n}{\epsilon}\right)^{\log \log n}$

- Define sampled subsets $V = S_0 \supseteq S_1 \supseteq \cdots \supseteq S_r \supseteq S_{r+1} = \emptyset$
- $S_i \leftarrow Sample(S_{i-1}, p_i)$

The choice of p_i determines the size of the emulator.



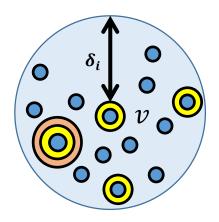
 $S_1 \leftarrow Sample(V, p_1)$



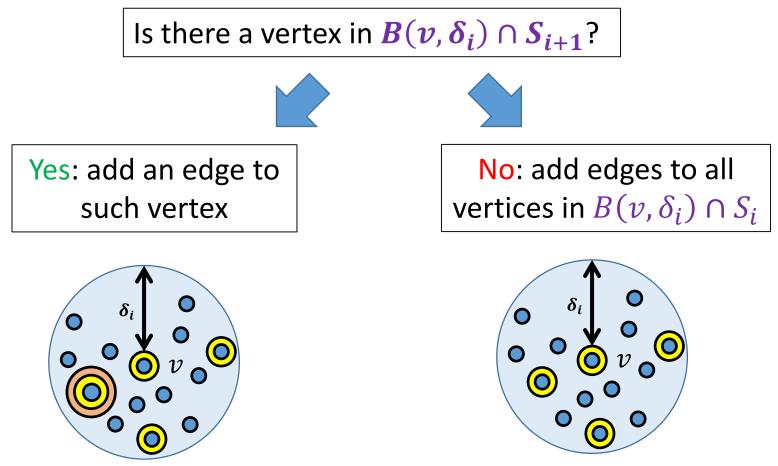
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A vertex in $v \in S_i$ looks at the ball of radius $\delta_i = \Theta(1/\epsilon^i)$

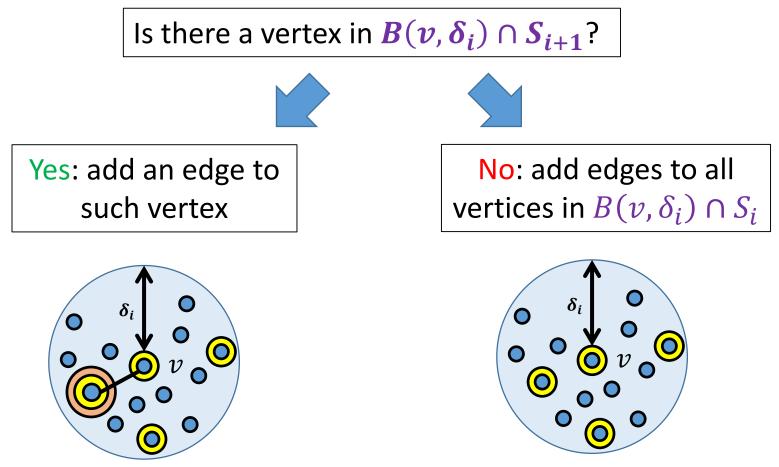
Is there a vertex in $B(v, \delta_i) \cap S_{i+1}$?



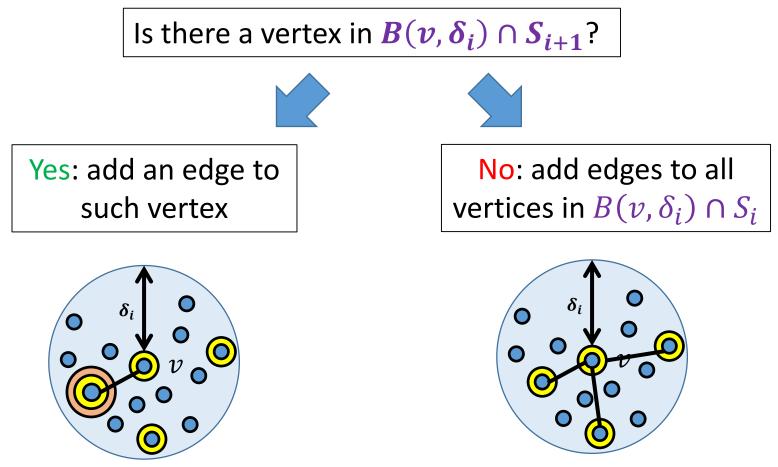
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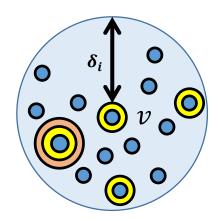
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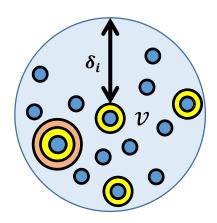


- Vertices inspect balls of radius δ_i
- Using the distance sensitive toolkit can be done in $poly(\log \delta_i)$ rounds



• *i*-clustered vertex: there is a vertex in S_i close-by

<u>Lemma</u>: if all vertices in the shortest u - v path are at most *i*-clustered, $d_H(u, v) \le (1 + \Theta(\epsilon i))d(u, v) + \Theta(\frac{1}{\epsilon^{i-1}})$



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$$\left(1 + \Theta(\epsilon r), \Theta\left(\frac{1}{\epsilon^{r-1}}\right)\right)$$
 stretch

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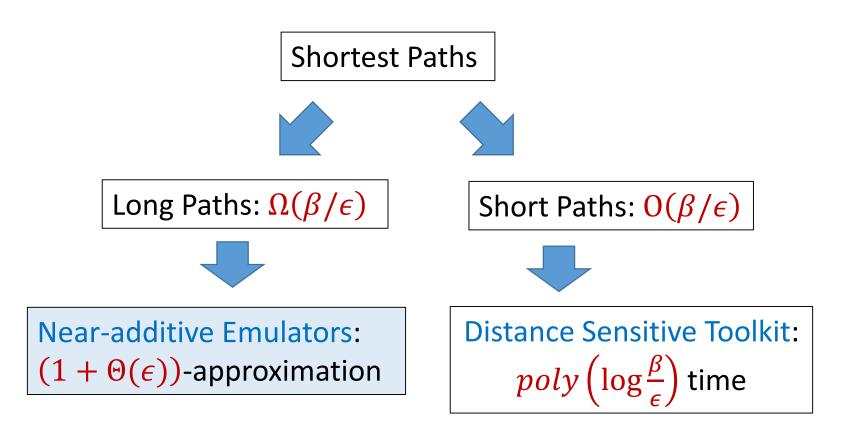
- Leads to $\left(1 + \Theta(\epsilon r), \Theta\left(\frac{1}{\epsilon^{r-1}}\right)\right)$ stretch
- After rescaling: $\left(1 + \epsilon, O\left(\frac{r}{\epsilon}\right)^{r-1}\right)$

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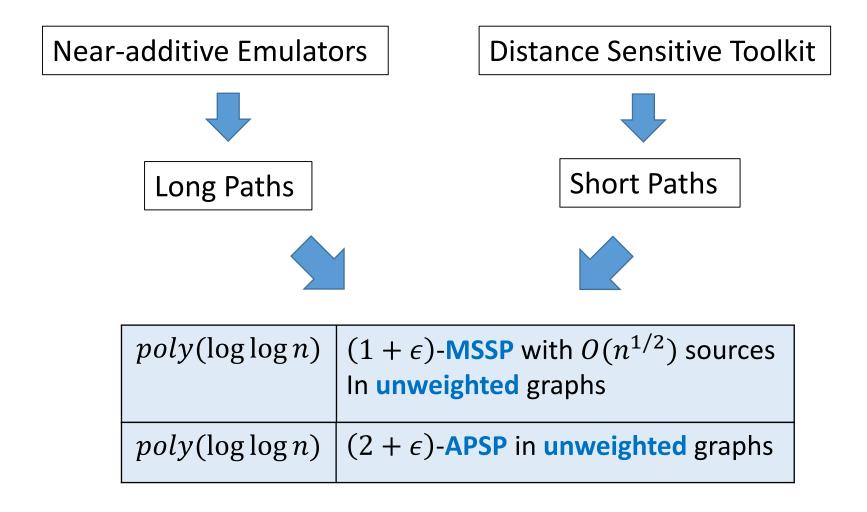
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- Leads to $\left(1 + \Theta(\epsilon r), \Theta\left(\frac{1}{\epsilon^{r-1}}\right)\right)$ stretch
- After rescaling: $\left(1 + \epsilon, O\left(\frac{\log \log n}{\epsilon}\right)^{\log \log n}\right)$

Shortest Paths via Emulators



Conclusion





poly(log log n) round algorithms for approximate shortest paths in the Congested Clique

Unweighted graphs:

$poly(\log \log n)$	•	$(1 + \epsilon)$ -MSSP with $O(n^{1/2})$ sources $(2 + \epsilon)$ -APSP
	•	$(1 + \epsilon, \beta)$ -APSP, $\beta = O\left(\frac{\log \log n}{\epsilon}\right)^{\log \log n}$

Open Questions

- Faster algorithms
- Weighted APSP
- Directed/exact shortest paths